NSW Foundation Spatial Data Framework:

Elevation and Depth Theme

Dataset/product title: Point Cloud

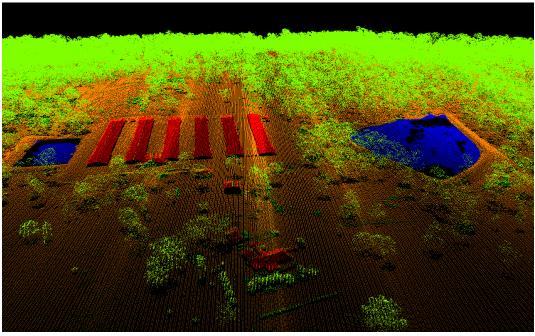


Image depicts sample of the NSW Point Cloud dataset © Spatial Services 2018

Dataset/product description	The point cloud data set consists of point clouds captured from LiDAR (Light Detection and Ranging) and derived from airborne imagery using photogrammetric techniques.
Dataset uses	This product has been produced for Spatial Services, local and state government and agency programs including Emergency Services. This product is also used on a whole of government basis as a visible record of the landscape at a given point in time, allowing for analysis to be carried out relating to flood modelling and water catchment management.
Current status	The LiDAR program is focused on the entire coast of NSW and west to the Great Dividing Range. Additionally, the program extends to rural towns in the central and western Divisions. Photogrammetric point clouds have been generated from airborne imagery for the central and western divisions of NSW.

Standards and specifications	Metadata for the relevant Spatial Serices datasets complies with AS/NZS ISO 19115-2, ANZLIC Metadata Profile v1.1 and ISO 19139
	Intergovernmental Committee on Surveying and Mapping (ICSM) Guidelines for Digital Elevation Data
	Spatial Services: Elevation Data Products Specification and Description (LiDAR)
	Spatial Services: Elevation Data Products Specification and Description (Airborne Photogrammetry)
Access and licensing	Spatial Services, a division of the Department of Finance, Services and Innovation (DFSI) creates and manages Intellectual Property for the Crown in right of New South Wales.
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	All Intellectual Property which is owned by Spatial Services should only be loaded on any external cloud platforms if Spatial Services' Intellectual Property remains unchanged, maintained and preserved.
Metadata	Point Cloud
Updates	LiDAR point cloud data is updated in specific locations across NSW as required. An update of the photogrammetrically derived point cloud is not planned.

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